



**1. Basic Information**

<b>Program Title</b>	Biomedical Engineering
<b>Department offering the Program</b>	Biomedical Engineering
<b>Department Responsible for the Course</b>	Computers Engineering and Control Systems
<b>Course Code</b>	CSE252
<b>Year/ Level</b>	Level 200
<b>Specialization</b>	Minor
<b>Requirements</b>	MTH101
<b>Authorization data of course specification</b>	

<b>Teaching Hours</b>	Credit	Lectures	Tutorial	Practical
	3	2	1	1.5

**2. Course Aims**

No.	Aim
1	Apply dynamic models, block diagram analysis, bode plot analysis for controlling different systems.
3	Design lead and lag compensators to control a biomedical system and encourage in-self learning to know the most recent control system design techniques.

**3. Intended Learning Outcomes (ILOs):**

**A. Knowledge and Understanding:**

No.	Knowledge and Understanding
A8	Elementary science underlying different tools such as dynamic models
A12	Basics of design tools such as root locus

**B. Intellectual Skills**

No.	Intellectual Skills
B12	Create different tools such as dynamic models, bode plot analysis.

**C. Professional Skills**

No.	Professional Skills
C3	Carry out compensator design for a control system.
C4	Practice the neatness in design of lag and lead compensator.
C5	Use computational tools and electronic circuits to design control systems related to biomedical systems.

**D. General Skills**

No.	General Skills
D2	Work in stressful environment and within constraints.
D9	Refer to relevant literature effectively.

**4. Course Contents:**

No.	Topics	No. of weeks
1	Dynamic modeling	1-2
2	Block diagram analysis	3-4
3	First and second order system	5-6
4	Routh test	7,9
5	Root Locus	10-11
6	Bode Plot diagram	12
7	Nyquist analysis	13
8	Lead and lag Compensators	14

**5. Teaching and Learning Methods:**

No.	Teaching Method
1	Lectures
2	Discussion Sessions
3	Research Assignment

**6. Teaching and Learning Methods for Disabled Students:**

No.	Teaching Method	Reason
1	Make simple projects	To help them practice

**7. Student Evaluation:**

**7.1 Student Evaluation Methods:**

No.	Evaluation Method	ILOs
1	Mid Term Examination	A8,A12, B12



2	Practical Examination	A8,A12,B12,C3,C4,C5,D2
3	Semester work	A8,A12,B12,C3,C4,C5,D2,D9
4	Final Term Examination	A8,A12,B12

**7.2 Evaluation Schedule:**

No.	Evaluation Method	Weeks
1	Mid Term Examination	8
2	Practical Examination	13
3	Semester work	Every week
4	Final Term Examination	15

**7.3 Weighting of Evaluations:**

No.	Evaluation Method	Weights
1	Mid Term Examination	20%
2	Practical Examination	10%
3	Semester work	20%
4	Final Term Examination	50%
<b>Total</b>		100%

**8. List of References**

No.	Reference List
1	Golnaraghi F, Kuo BC. Automatic Control Systems. Wiley; 2009.
2	II RL, Lawrence DA. Linear State-Space Control Systems. John Wiley & Sons; 2007.
3	Dorf RC, Bishop RH. Modern Control Systems. Prentice Hall; 2011.
4	Nise NS. Control Systems Engineering. Wiley; 2014.

**9. Facilities Required for Teaching and Learning:**

No.	Facility	No.	Facility
1	White Board	3	Sound System
2	Data Show System	4	Wire-Internet

**10. Matrix of Knowledge and Skills of the Course:**

N o.	Topic	Aims	Knowledge & Understanding	Intellectual Skills	Professional Skills	General Skills
1	Dynamic modeling	1	A8	B12	C3	
2	Block diagram analysis	1,3	A12	B12,	C3	D2
3	First and second order system	1,3	A8,	B12	C3,C5	D2
4	Routh test	1	A8,A12	B12,	C3,C5	D2
5	Root Locus	1,3	A8,A12,		C3,C4	D2
6	Bode Plot diagram	1,3	A12	B12	C3	D2,D9
7	Nyquist analysis	1	A8		C3,C4	D2
8	Lead and lag Compensators	1	A12	B12	C3,C4,C5	D2,D9

**Course Coordinator: Prof. Dr.**

**Head of Department: Assoc. Prof. Hossam Eldeen Moustafa**

**Date of Approval:**